



TinyMobileRobots

# Agenda

1. TinyMobileRobots
2. The TinySurveyor Robot solution
3. TinySurveyor Terra & Plotter
4. Applications
5. Features
6. Data logging



# 2015

Headquarter established in Denmark

# +100

Employees with in-house R&D and production teams & TinyMobileRobots US

# 4

Different autonomous robot models for high precision marking and stake-out in operation globally

# +20

National distribution partners in North America, Europe and the Pacific regions



# Your new colleague

## **What is the TinySurveyor?**

The TinySurveyor is the ultimate high-precision instrument for the surveying and infrastructure industries. It has an unparalleled ability to execute large tasks up to 10x faster than traditional surveying and stake-out methods.

## **What does it solve?**

The TinySurveyor performs pre-marking, stake-out / set-out, data collection, as-built surveys etc. In short, it increases quality, efficiency and safety in the infrastructure industry.

## **Who can benefit?**

Land surveyors, road construction companies, civil engineering companies, construction companies, airport maintenance services etc.



# Key features

- **Fast:** Significant time savings (fast and agile)
- **Safe:** Can be remote operated from a safe distance (beacon, ultrasound collision detection, fit-a-flag option)
- **Easy to use:** User-friendly tablet solution
- **GNSS / Total Station:** Brand independent
- **Lightweight and portable:** 18-25 kg excl battery
- **Performance:** High accuracy and long-lasting battery
- **Data:** Common data formats (DXF and CSV)



# System overview

**GNSS/Total station**



**TinySurveyor Robot**



**TinySurveyor App**



# TinySurveyor App workflow



- Load existing job via USB or Computer
- Use DXF and CSV files



- Create new job from template (geometric shapes, parking lot, coverage area etc.)
- Collect data to create new job

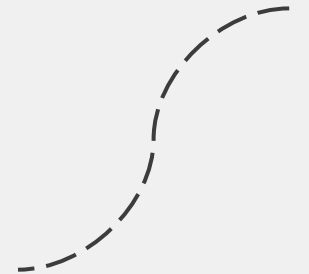
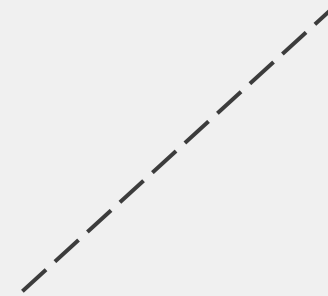


- Automatic and manual driving mode
- Real-time visualization of task execution
- Edit, copy and offset points and lines directly from tablet

# Your design file laid out

## Mark points, lines, splines and curves

- Ability to pick up and set out points and lines from GNSS or total station
- Load points and lines via DXF or CSV files
- Set operating speed, wait time at points, and spray duration, etc....
- Auto-resume functionality
- Lay out complex designs
- Customize your points and lines (point diameter, line dashing, intervals, etc.)







## TinySurveyor Plotter

- “On-Road”
- Designed for road works and “solid” surfaces
- Extra safety features
- Extra connectivity features



## TinySurveyor Terra

- “Off-Road”
- Designed for both solid and uneven surfaces
- The multipurpose robot for layout, stakeout, surveying, etc.

# Potential TS Plotter

## Pre-marking

- Roads
- Parking lots
- Airports
- Indoor

## As-built survey



# Potential TS Terra

- Large-scale stake-out
- Pre-marking
- As-built survey
- Topography



# Key outcomes

- **Labor cost savings:** 60-90%
- **Productivity:** Complete more work faster
- **Mobility:** Deployed in minutes
- **Performance:** Tirelessly executes large tasks
- **Worker health & safety:** Safer work environment for surveyors and operators. No bending over to put marks on the ground.

# Quality

- Repeatable results with GNSS and Total Station
- Accuracy 2 cm / 0.8 in using GNSS
- 10 Millimeter precision using total station
- Customer evaluations show substantial quality improvements in project execution

# Efficiency

- Stake out 2-600 points per hour
- 5-10x times faster than traditional methods
- No longer need to stop, level and bend to mark out points or lines
- Operation for min. 8 hours on one battery charge
- Rugged tablet to operate the TinySurveyor even in demanding weather conditions
- Efficient reduction in use of paint required

# Safety

- Operate from the safety of a vehicle or behind safety barriers
- Reduce fatigue and body strain on operator
- Operator can stay out of live traffic areas and never has to be facing away from traffic
- Emergency stop





# Applications

# Road pre-marking

*“Example of TinySurveyor being 5 times faster than a person and delivering better result.”*

## **Speed**

The TinySurveyor can tirelessly execute large tasks at 4 km/hour / 2.5 mph, allowing surveyors and road marking companies to complete pre-marking 5-10 times faster than usual.

## **Workflow integration**

Existing CAD data allows the TinySurveyor to instantly mark out points, lines and arches before permanent markings.

## **Accuracy**

GNSS connectivity yields an accuracy of 2 cm / 0.8 in. Integrating with a total station allows for millimeter precision.

**TinyMobileRobots**

# Airport

*“What would have taken five weeks, this little robot has done in one week.”*

## **Safety**

No need for any person to be on any runway or traffic zone.

## **Workflow integration**

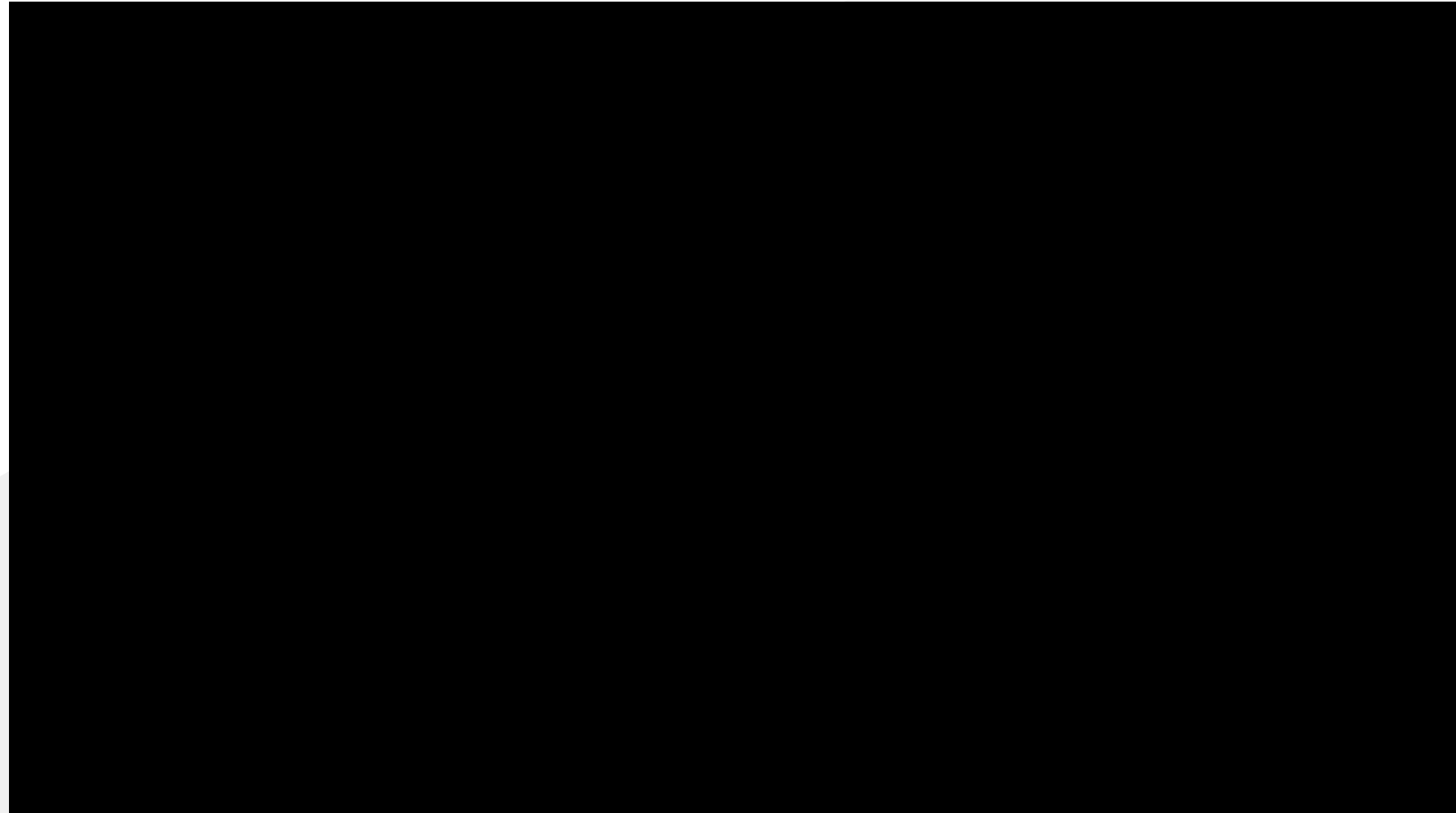
Existing CAD data allows the TinySurveyor to instantly mark out points, lines and arches before permanent markings.

## **Speed**

The TinySurveyor can tirelessly execute large tasks at 2.5 mph completing tasks much faster, giving more flexibility in a time limited industry. Operating day and night helps reducing costly disruptions to flights.

## **Accuracy**

GNSS connectivity yields an accuracy of 2 cm / 0.8 in. Integrating with a total station allows for millimeter precision.



# Car park set-out

## **More resources**

Using a pre-marking robot for car park set-out is much faster than traditional stake-out methods. The surveyor or operator can focus on project critical tasks instead of rudimentary line marking.

## **Productivity**

With more than 8 hours continued use on one battery charge and with data well prepared, this automated layout process can dramatically increase productivity on large-scale projects.

## **Density**

More information is provided on the ground for the line painting crew to instantly start painting without any interpretation.





# Drill hole set-out

## **Robust**

The rugged design and high traction wheels operate in a variety of environmental conditions.

## **Reduce downtime**

Drill patterns can be set out quickly, reducing heavy machinery downtime.

## **Safety**

Removes operators from heavy machinery as well as live traffic.



# Harbor set-out

## **Robust**

The high traction motor wheels enable TinySurveyor to operate on a variety of surfaces, including sand.

## **Repeatability**

Reliable and efficient positioning means that the TinySurveyor can mark up to 300 points per hour on sand and up to 600 points per hour on hard surfaces.

## **Quality**

With CAD data prepared and sent to the TinySurveyor via tablet, this automated layout process gives a very high accuracy every time.



# Construction set-out

*“Does foundation layout 2-3 times faster than 1 person with a Total Station.”*

## **Speed**

The TinySurveyor can tirelessly execute large tasks at 4 km/hour / 2.5 mph, allowing surveyors complete marking e.g. perimeter foundation up to 2-3 times faster than usual.

## **Workflow integration**

Existing CAD data allows the TinySurveyor to instantly mark out points, lines and arches.

## **Accuracy**

GNSS connectivity yields an accuracy of 2 cm / 0.8 in. Integrating with a total station allows for 10-millimetre precision.



# Outdoor stake-out

*“Stake-out 2-600 points per hour depending on terrain and distance between points.”*

## **Robust**

The rugged design and high traction wheels operate in a variety of environmental conditions.

## **One person**

The TinySurveyor will mark the ground and a single person can stake, pin or peg the locations of the pilings.

## **Speed**

Complete the stake-out tasks quickly to allow other trades to get to work faster, improving project productivity.

## **Accuracy**

GNSS connectivity yields an accuracy of 2 cm / 0.8 in.



# Railway set-out

## **Speed**

The TinySurveyor can tirelessly execute large tasks at 4 km/hour / 2.5 mph, allowing surveyors complete marking e.g., the centre line up to 10 times faster than usual.

## **Workflow integration**

Existing CAD data allows the TinySurveyor to instantly mark out points, lines and arches.

## **Accuracy**

GNSS connectivity yields an accuracy of 2 cm / 0.8 in. Integrating with a total station allows for 10-millimetre precision.



# Indoor

*“Made it possible to transfer our height curve CAD file to the actual floor.”*

## **Versatile**

Total station integration gives the TinySurveyor the ability to work in any location.

## **Maneuverability**

The compact design makes the TinySurveyor ideal for staking out and driving between small spaces at construction sites.

## **Speed**

Complete the set-out tasks quickly to allow other trades to get to work faster, improving project productivity.

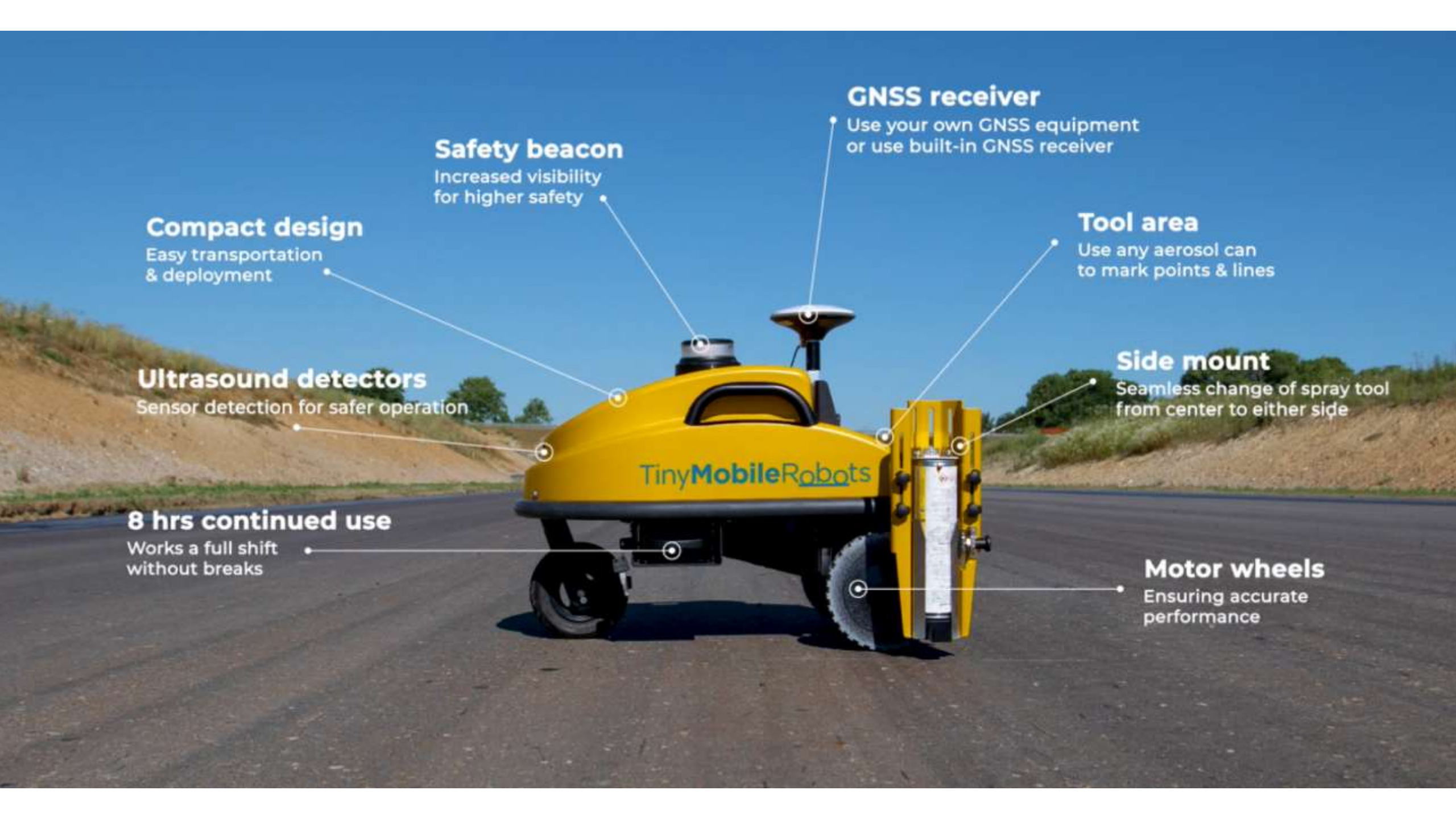
## **Accuracy**

The TinySurveyor can operate at an accuracy of 10 mm / 0.4 in when integrating with a total station.





# Features



### GNSS receiver

Use your own GNSS equipment or use built-in GNSS receiver

### Safety beacon

Increased visibility for higher safety

### Compact design

Easy transportation & deployment

### Tool area

Use any aerosol can to mark points & lines

### Ultrasound detectors

Sensor detection for safer operation

### Side mount

Seamless change of spray tool from center to either side

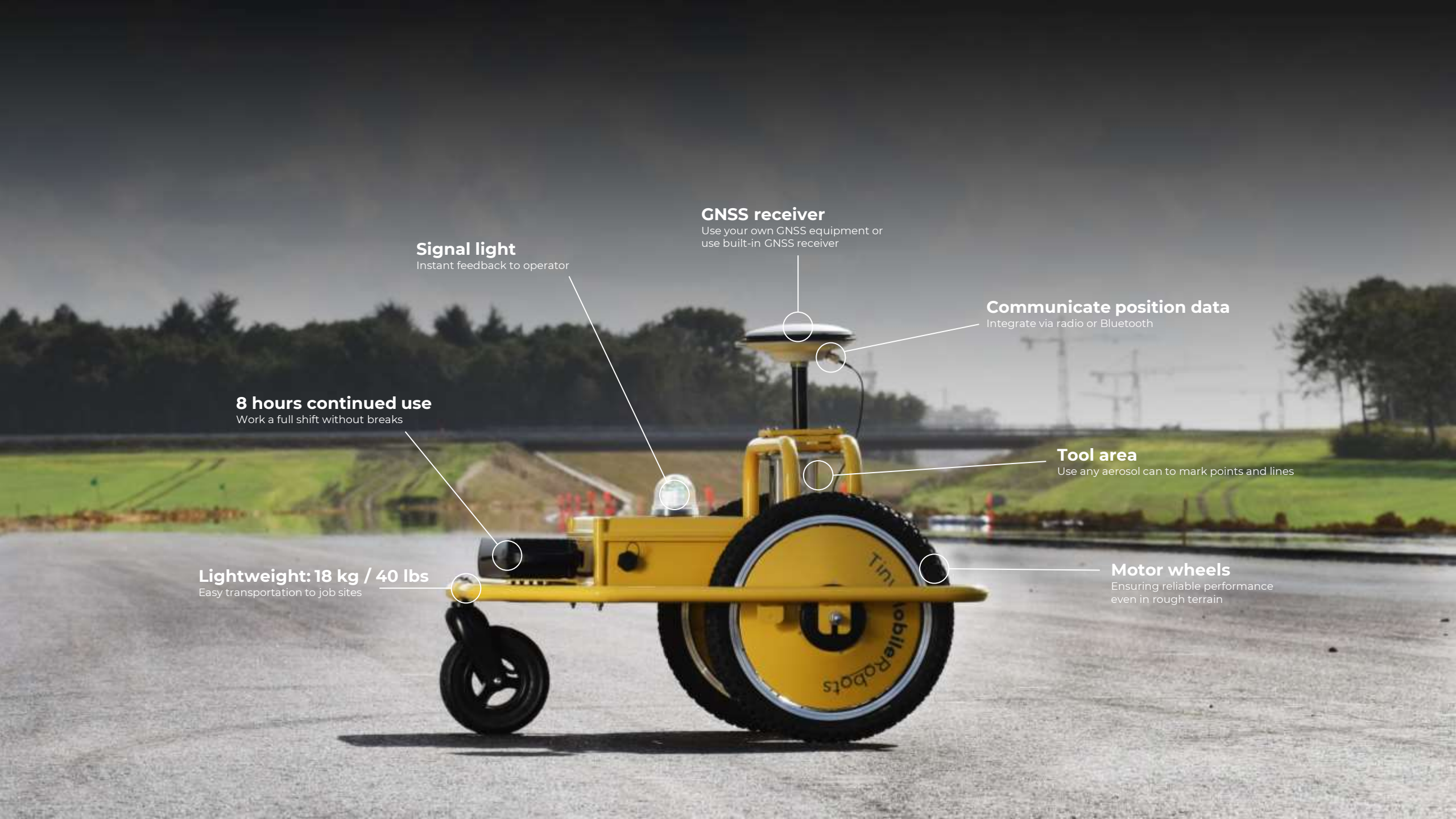
### 8 hrs continued use

Works a full shift without breaks

### Motor wheels

Ensuring accurate performance





**GNSS receiver**

Use your own GNSS equipment or use built-in GNSS receiver

**Signal light**

Instant feedback to operator

**Communicate position data**

Integrate via radio or Bluetooth

**8 hours continued use**

Work a full shift without breaks

**Lightweight: 18 kg / 40 lbs**

Easy transportation to job sites

**Tool area**

Use any aerosol can to mark points and lines

**Motor wheels**

Ensuring reliable performance even in rough terrain

# Side mount

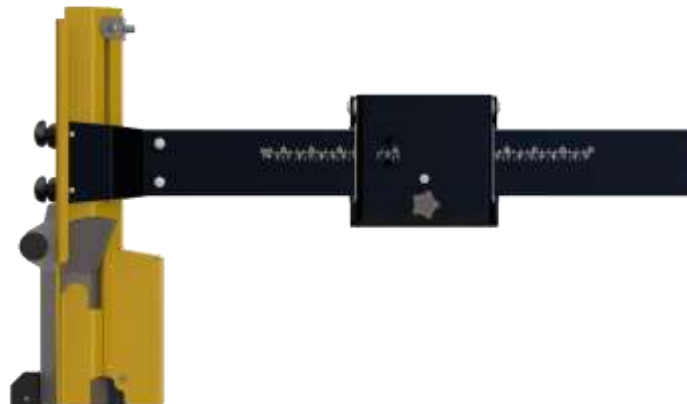


- Reposition the spray tool to fit the task at hand
- Easily move the spray tool to the left or right side of the TinySurveyor
- Drive near edges on road works
- Simple configuration on user tablet
- Adjust spray tool height using built-in handles
- Used for: Edge seal, barriers, kerbing, driving near asphalt slab edges etc.



# Side mount

- Reposition the spray tool to fit the task at hand (up to 58cm/23in left – 42cm/16.5in right)
- Easily move the spray tool to the left or right side of the TinySurveyor not needing tools
- Drive near edges on road works
- Simple configuration on user tablet
- Adjust spray tool height using built-in handles
- Used for: Edge seal, barriers, kerbing, driving near asphalt slab edges etc.



# New data logging feature



ROBOT  
Creates Data Log in Real-time

TABLET via BlueTooth  
or  
USB

Format & Export .CSV



LOG Files  
Stored on Robot Internal Memory



# What will be logged?

## POSITION DATA

Calibrated Tool Coordinates, Antenna Coordinates (RAW + Proj.), Planned Coordinates

## ACCURACY DATA

Standard Deviation from external GNSS via GPGST - latitude, longitude, altitude, RMS value

## SURVEYED POINTS

Calculated average coordinates of time-series position data collected at stationary waypoint

## ROBOT SETTINGS

Input Source, Tool Position, Tool Sideshift, Tool Height, Line Length, etc...

# When & Why will it be logged?

The background image shows a construction site on a road. In the foreground, a yellow autonomous robot is visible on the right side of the road. In the distance, a blue machine, possibly a sprayer, is working on the road surface. The scene is dimly lit, suggesting an overcast or foggy day.

## LOG SPRAY

Whenever the spray tool does something...  
Used to log where paint is applied on the surface

## LOG DRIVING

Whenever the Robot drives autonomously...  
Used to track when and where the robot has been

## SURVEY POINTS

Whenever the robot reaches a waypoint...  
Increased accuracy of static point coordinates

# Log Data

New tab in settings menu

The screenshot shows a settings application with a sidebar menu on the left and a main content area on the right. The sidebar menu includes options for General, Position, Robot behaviour, Log Data (which is currently selected), Communication, Internet, Templates, User, and Help. The main content area is titled 'Log Data' and contains a 'Logging' section. This section includes a text input for 'File name' with the value 'Test log 1', a 'Log spray' checkbox that is checked, a 'Log driving' checkbox that is checked, and a 'Survey point' checkbox that is unchecked. There are two radio buttons for logging frequency: 'Distance' (selected) and 'Time'. To the right of these are two dropdown menus: 'Log lines every' set to 30 cm and 'Log position every' set to 30 cm. At the bottom right of the logging section is a 'Wait time' dropdown set to 0 sec. A 'Transfer Log Files' button is located at the bottom of the logging section.

**Settings**

- General
- Position
- Robot behaviour
- Log Data**
- Communication
- Internet
- Templates
- User
- Help

**Log Data**

**Logging**

File name

Log spray

Log driving   Distance  Time

Survey point

Log lines every  cm

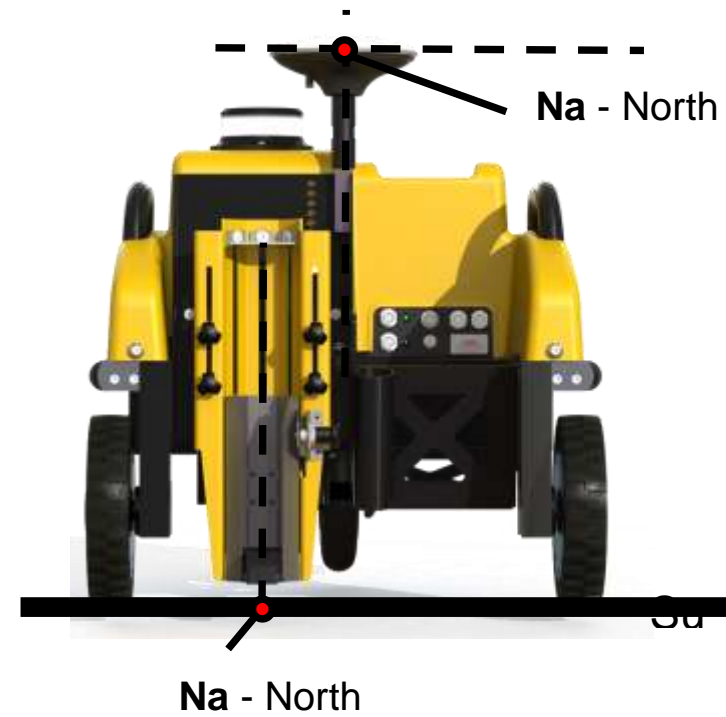
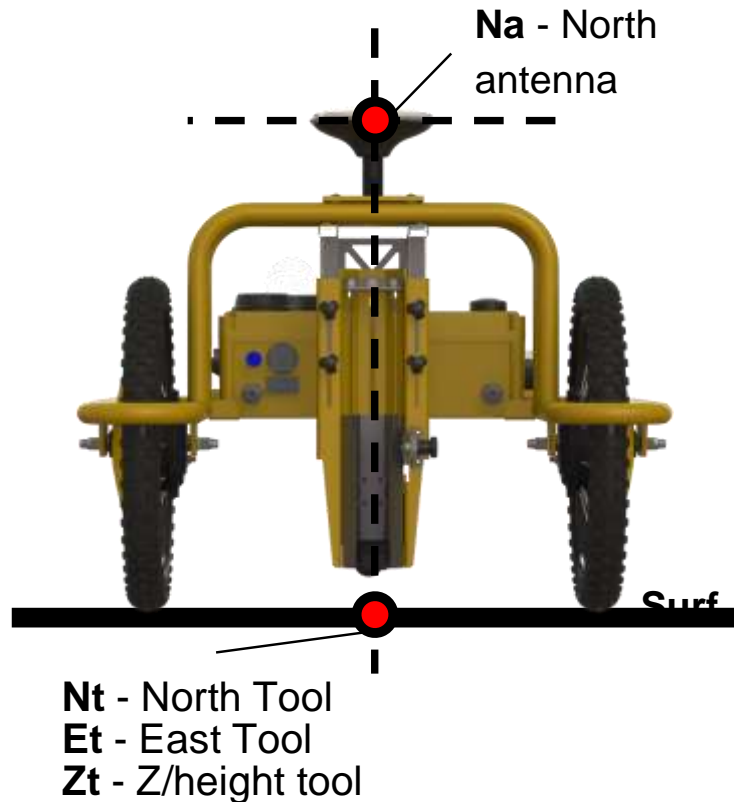
Log position every  cm

Wait time  sec

**Transfer Log Files**

# Tool vs. Antenna

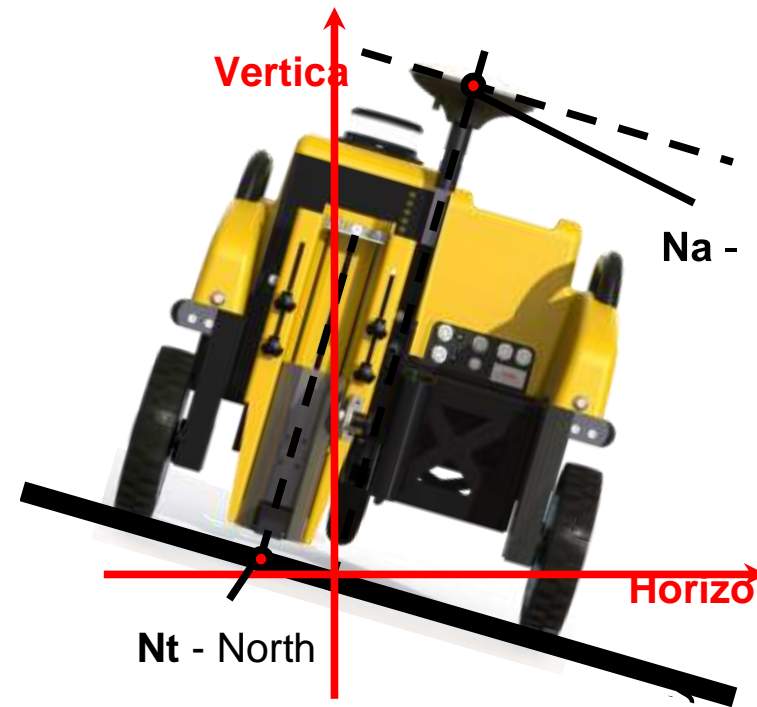
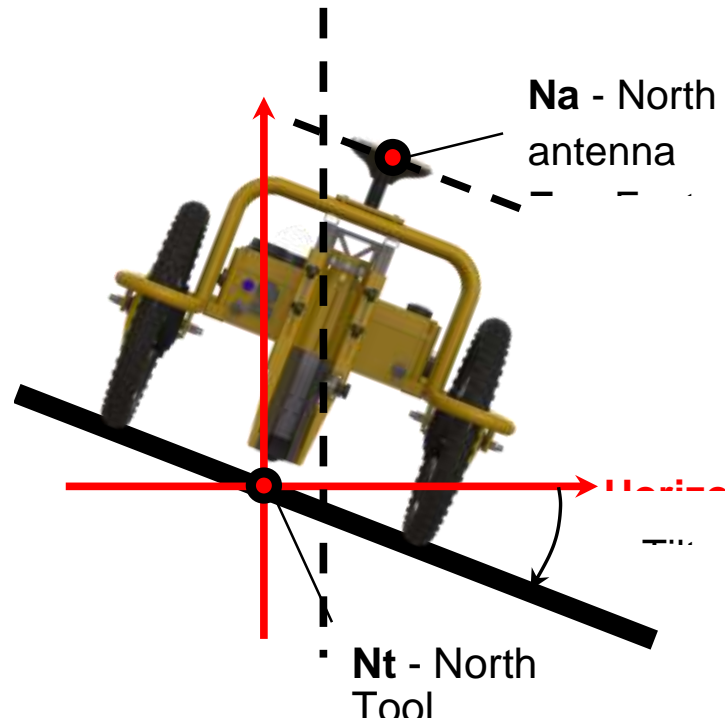
- Flat horizontal surface



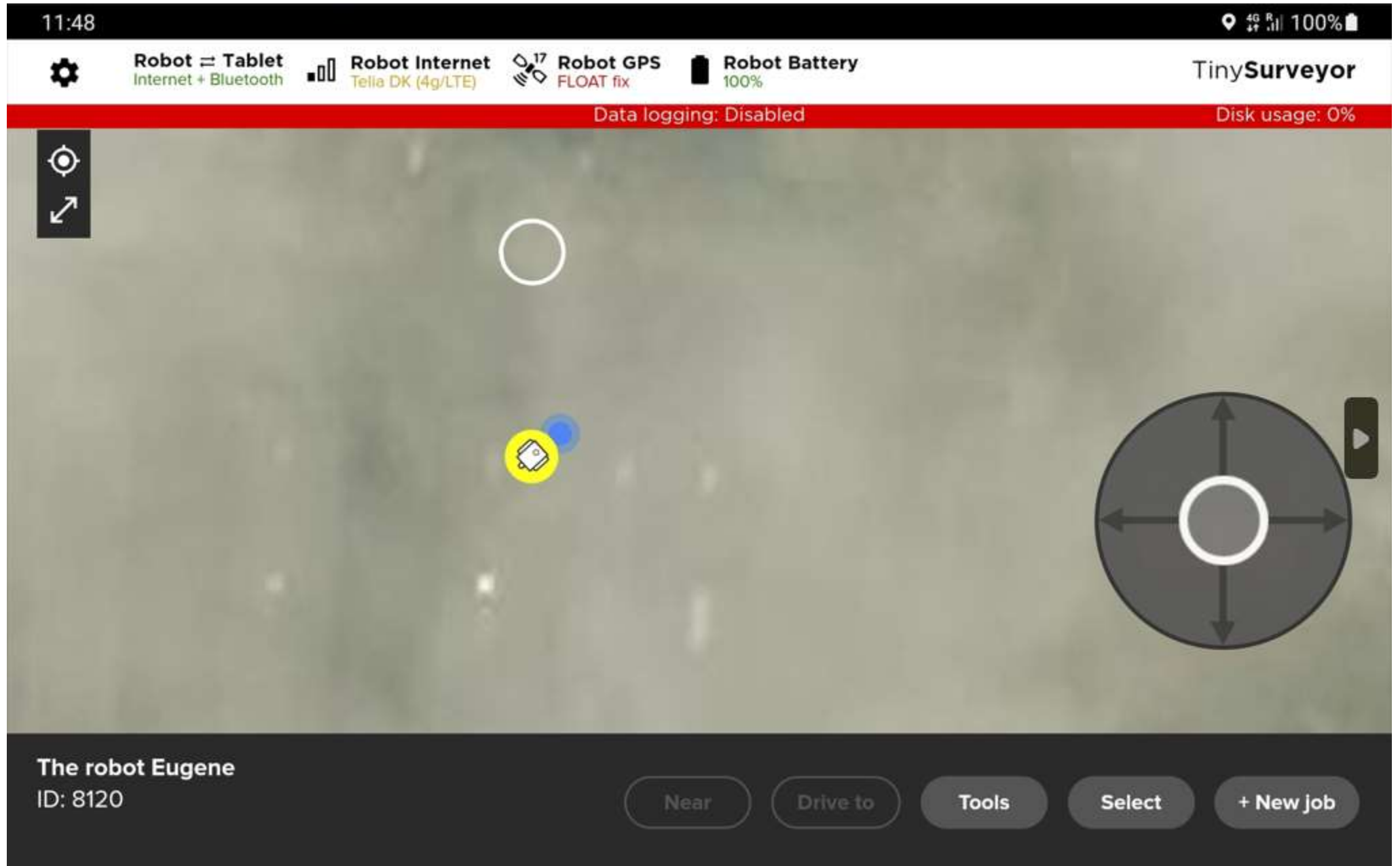


# Tool vs. Antenna

- Tilted horizontal surface



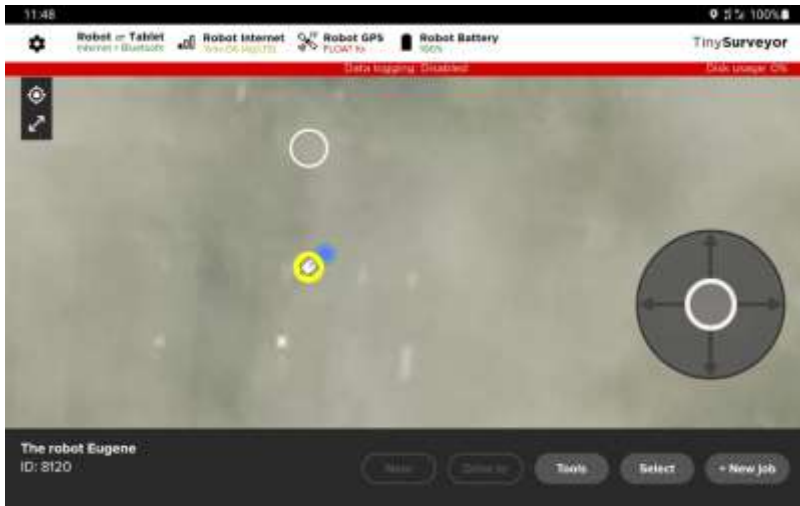
# Data Logging Status Bar



# Data Logging Status Bar

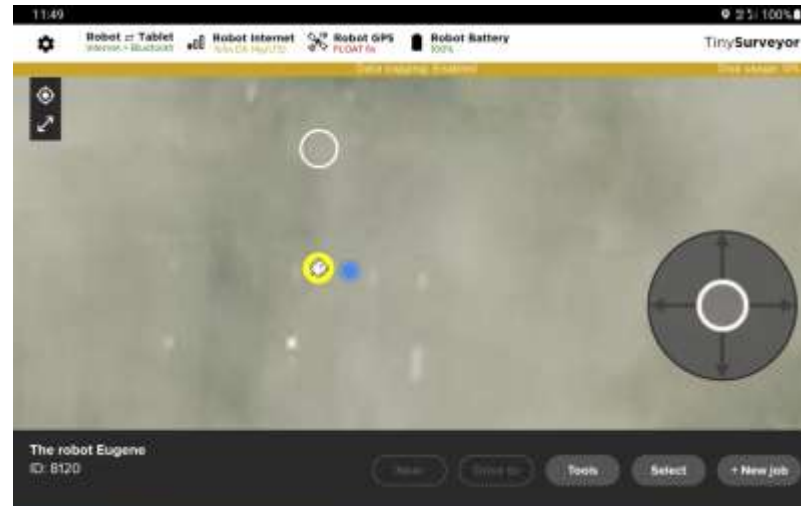
A highly visible status bar has been added to the map screen to ensure you don't forget to activate logging when on the job. It's accompanied by a data storage % to let you know when storage is getting limited on the robot.

Disabled



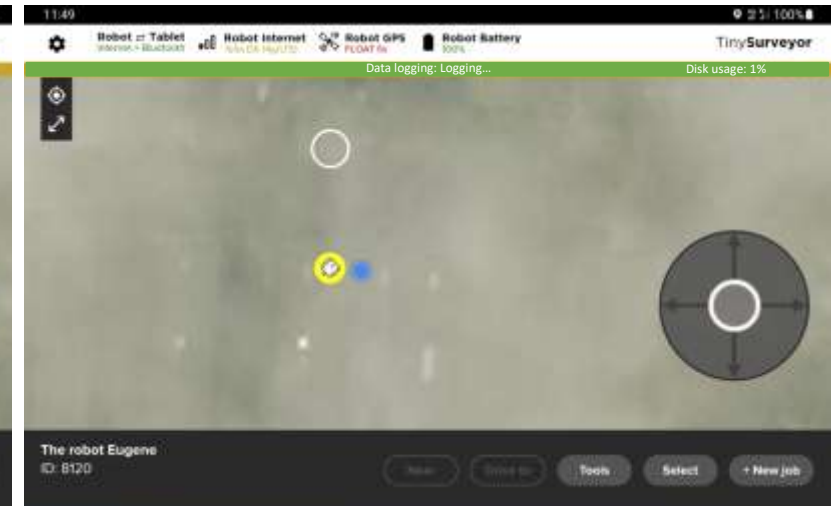
When no logging options are enabled. Don't forget to activate logging options if you want to record data.

Enabled



When one or more logging options are enabled. This means Logging is armed and ready to go.

Logging...



When the robot is executing a task/job and data is being logged.

# Thank you

A yellow autonomous road marking robot is shown in the foreground, painting a dashed white line on a road. In the background, a yellow tractor is parked on the side of the road. The scene is set on a road with a grassy embankment and a bridge in the distance under a clear blue sky.

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