Trimble MX9

MOBILE MAPPING SOLUTION

KEY FEATURES

- Very high point cloud density with complementary immersive imagery
- ► State of the art Trimble® GNSS and Inertial technology
- Lightest and most compact premium mobile mapping system
- ► Simple installation and browser-based operation from any smart device
- ► Compatible with existing Trimble software and workflows
- ► Enhanced remote support capabilities
- Supported by Trimble Business Center Mobile Mapping for efficient data processing





Trimble MX9 MOBILE MAPPING SOLUTION

MX9 SYSTEM		
Scan speed	500 scans/sec	
Number of laser scanners	2	
Laser positions	Adjustable in 3 horizontal and 3 vertical positions	

MX9 LASER SCANNER Laser class 1, eye-safe EFFECTIVE 300 500 1000 1250 1500 1800 MEASUREMENT RATE¹ kHz kHz kHz kHz kHz kHz kHz kHz kHz Maximum range target 475 m 370 m 235 m 235 m 235 m 235 m	
EFFECTIVE 300 500 1000 1250 1500 1800 MEASUREMENT RATE¹ kHz kHz <td></td>	
MEASUREMENT RATE¹ kHz kHz kHz kHz kHz kHz Maximum range target Reflectivity > 80%² MEASUREMENT RATE¹ kHz kHz kHz kHz kHz kHz kHz	
Reflectivity > 80% ²	_
Maximum range target 170 m 120 m 95 m	
Reflectivity > 10% ²	
Maximum number of targets per pulse up to 15 up to 15 up to 9 up to 7 up to 5 up to	o 4
Minimum range $1 \text{ m @ PRR} \ge 1 \text{ MHz}, 1.2 \text{ m @ PRR} < 1 \text{ MHz}$	
Accuracy³/precision⁴ 5 mm/3 mm	
Field of view 360° "full circle"	

EMBEDDED	TRIMBLE GNSS-INERTIAL SYSTEM
IMU-Options	AP60
ACCURACY—NO GNSS O	OUTAGES (POST PROCESSED)⁵
X, Y position (m)	0.020
Z position (m)	0.050
Velocity (m/s)	0.005
Roll and pitch (deg)	0.005
Heading (deg) ⁷	0.015
ACCURACY-60 SECOND) GNSS OUTAGE (POST PROCESSED)⁵
X, Y position (m)	0.100
Z position (m)	0.070
Roll and pitch (deg)	0.005
Heading (deg) ⁶	0.015
ACCESSORIES	
GAMS	Yes, optional
DMI ^{5,7}	Yes, optional

CAMERAS				
SPHERICAL CAMERA				
Camera type	No	Mounting	FoV	Focal length
30 MP (6 x 5 MP)	1	Fixed	90 % of full sphere	4.4 mm
Capture modes	By distance or by time at 10 fps max			
PLANAR CAMERAS				
Camera type	No	Mounting	FoV	Focal length
12 MP side facing camera	2	Adjustable (in horizontal and vertical positions)	H: 47.6° V: 35.9°	16.0 mm
12 MP backward/ downward facing camera	1	Fixed	H: 82.9° V: 65.9°	8.0 mm

ELECTRICAL DATA		
Power supply input voltage	12 V-DC (12 V-16 V)	
POWER CONSUMPTION		
Max	350 W	
Typical	280 W	

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SYSTEM CC	MPONENTS
Sensor unit	Included
Control unit	Included
Power unit	Included
Roof rack	Included, standard cross bars not included
Transport box	Included
Field software	TMI, browser-based, no installation necessary
Cable, battery to power unit	5 m
Cable, power unit to control unit	3 m
Cable, control unit to sensor unit	5 m
Data storage	1 set (2 x 2 TBytes SSD, removable) ⁸
Control interface	Tablet or Notebook, Wi-Fi or LAN cable, byod

3RD PARTY HARDWARE	INTEGRATION OPTIONS

Synchronization output at sensor unit 1 (NMEA + PPS)

ENVIRONMENTAL CHARACTERISTICS		
Maximum vehicle speed for data acquisition	110 km/h (68 mph)	
IP rating	IP64 (sensor unit)	
Operating temperature	0 °C to +40 °C	
Storage temperature	-20 °C to +50 °C	
Relative humidity (operating)	20 % to 80 %	
Relative humidity (storage)	20 % to 95 %	

PHYSICAL CHARACTERISTICS		
Dimensions sensor unit	0.62 m x 0.55 m x 0.62 m	
Weight sensor unit	37 kg	
Dimensions roof rack	1.03 m x 0.48 m x 0.28 m	
Weight roof rack	18 kg	

- Rounded values, selectable by measurement program. Typical values for average conditions. Accuracy is the degree of conformity of a measured quantity to its actual (true) value. Precision is the degree to which further measurements show the same results.

- Precision is the degree to which further measurements show the same results.
 With DMI option.
 With GAMS option, 2 m baseline
 One sigma values, with DMI option, post-processed using base station data. Typical performance. Actual results are dependent upon satellite configuration, atmospheric conditions and other environmental effects.
 4 TBytes SSD is available as an accessory.

Specifications subject to change without notice.



Contact your local Trimble Authorised Distribution Partner for more information

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