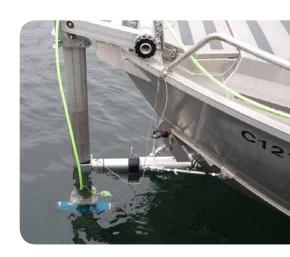
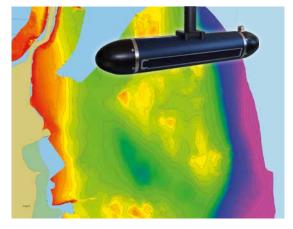


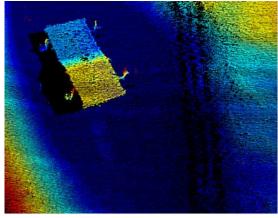
# 3D side scan sonar

## Ping DSP, 3DSS-DX-450

- **⊘** 3D underwater imaging and mapping
- **⊘** Unique signal processing method "CAATI"
- Spans the entire watercolumn from seabed to surface
- Superior wide swath bathymetry
- **⊘** Compact, low power and easy-to-use







#### **Wide Swath Bathymetry**

High resolution swath bathymetry coverage of up to 14 times water depth. State-of-the-art acoustic transducer technology, based upon the unique and patented CAATI signal processing, provide superior swath bathymetry performance by separating backscatter arrivals from the seabed, sea-surface, water-column and multipath.

#### **Real Time 3D Sidescan Imagery**

3D Sidescan imagery spans the entire water column and extends 2D sidescan resolution capabilities to three dimensions. Revolutionary Sidescan3D™ software displays stunning 3D imagery in real time. The 3DSS-DX-450 target logger feature allows easy capture and inspection of 3D objects and seabed views to augment bathymetry with colocated, geometrically correct views of structures, pipes, cables, pilings, debris, hazards, habitats, vegetation and other finescale features of the seabed.



### Patented array signal processing technology (CAATI)

The 3DSS-DX-450 incorporates a patented signal processing methodology that extends the single angle-of-arrival principle used in interferometric systems to accommodate multiple simultaneous

backscatter arrivals (e.g. the seabed, sea surface,water-column, and multipath). The result is true 3D sidescan imaging and superior swath bathymetry from a compact, easy-to-use sonar.

#### **SONAR SPECIFICATIONS**

Operating Frequency450 kHzHorizontal Beamwidth (2 way)0.4°Vertical Beamwidth (selectable)15° - 125°Mech. Transducer Tilt (fixed)20°Electronic Transmit Tilt-45° to 45°Max. Ping Rep. Rate~30 Hz



#### **SPECIFICATION 2D AND 3D IMAGERY**

2D 3D

Data Output Range and Amplitude Range, Angle, and Amplitude

Max Range200 m per side100 m per sideMax Resolution1.67 cm1.67 cm

Typical 2D Imaging Swath Width 10 to 20 times sonar altitude depending on sound profile and bottom type
Typical 3D Bathymetry Swath Width 6 to 14 times sonar altitude, varies with sound velocity profile and bottom type

#### **BATHYMETRY SPECIFICATIONS**

Typical Bathymetry Swath Width 6 to 14 times sonar altitude, varies with sound velocity profile and bottom type

Max Bathymetry Range per Side 100 m per side

#### INTEGRATED MRU SPECIFICATIONS

Roll & Pitch 0,5°

#### **INTERFACE SPECIFICATIONS**

External input: 1 PPS, RS-232 interface, NMEA and TSS protocols

Computer Requirements: PC (Quad Core, 8GB, Discrete GPU (e.g. Nvidia), MS Windows 7 or 8 (64 bit)

3<sup>rd</sup> Party Software Support: QINSy, PDS2000, Hypack, SonarWiz

#### PHYSICAL SPECIFICATIONS

Voltage Requirements 24 VDC +/- 10%

Power Consumption 17 W idle, 22W typical (current: 0.7A idle 0.9A typical average, 3A max for 2sec., 7A peak)

Dimensions 56,8 cm (length), 9,8 cm (diameter)

Weight 8 kg (in air)
Depth Rating 10 m

The published information has been compiled with care. Nevertheless Geometius can not be held responsible for any inaccuracies, misunderstandings and consequences liable.